

Lin. Algebra UE

- X) 12.3: 1, 4
 12.4: 2, 3a, 7
 12.5: 2, 4, 8

$$12.3.1) (\mathbb{R}^{3 \times 1}, \nu) \quad \nu(E, E) = \text{diag}(1, 1, -1)$$

$$\in L(\mathbb{R}^{3 \times 1}, \mathbb{R}^{3 \times 1})$$

$$\langle E^*, \hat{f}(E) \rangle = \begin{pmatrix} 0 & -2 & -4 \\ 2 & 0 & -1 \\ -4 & -1 & 0 \end{pmatrix}$$

ges.: $\langle E^*, \hat{f}(E) \rangle$, ZZ: f normal.

$$\hat{f} = d_{\mathbb{R}^{3 \times 1}}^{-1} \circ f^T \circ d_{\mathbb{R}^{3 \times 1}} \Leftrightarrow \langle E^*, \hat{f}(E) \rangle = (\nu(E, E))^{-1} \cdot \langle E^*, f(E) \rangle^T \cdot \nu(E, E)$$

$$\langle E^*, \hat{f}(E) \rangle = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -2 & -4 \\ -2 & 0 & -1 \\ -4 & -1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 2 & 4 \\ -2 & 0 & 1 \\ 4 & 1 & 0 \end{pmatrix}$$

$$\langle E^*, f(E) \rangle \langle E^*, \hat{f}(E) \rangle = \begin{pmatrix} -12 & -4 & -2 \\ -4 & 3 & 8 \\ 2 & -8 & -17 \end{pmatrix} = \langle E^*, \hat{f}(E) \rangle \langle E^*, f(E) \rangle$$

$$\Rightarrow f \circ \hat{f} = \hat{f} \circ f, \text{ d.h. } f \text{ normal.}$$

$$12.4.3a) A := \frac{1}{7} \begin{pmatrix} -3 & 2 & 6 \\ -6 & -3 & -2 \\ 2 & -6 & 3 \end{pmatrix}$$

Drehwinkel φ :

$$\cos \varphi = \frac{\text{tr} A - 1}{2} = \left(-\frac{3}{7} - 1\right) \cdot \frac{1}{2} = -\frac{5}{7} \Rightarrow \varphi = \arccos\left(-\frac{5}{7}\right) = 0,7532 \dots \pi \approx 135,6^\circ$$

Drehachse $[G_1]$:

$$A + A^T - (\text{tr} A - 1)E_3$$

$$= \frac{1}{7} \left(\begin{pmatrix} -3 & 2 & 6 \\ -6 & -3 & -2 \\ 2 & 6 & 3 \end{pmatrix} + \begin{pmatrix} -3 & -6 & 2 \\ 2 & -3 & 6 \\ 6 & -2 & 3 \end{pmatrix} - \begin{pmatrix} -10 & 0 & 0 \\ 0 & -10 & 0 \\ 0 & 0 & -10 \end{pmatrix} \right) = \frac{1}{7} \begin{pmatrix} 4 & -4 & 8 \\ -4 & 4 & -8 \\ 8 & -8 & 16 \end{pmatrix}$$

l.o.

$$\Rightarrow [G_1] = \left[\begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \right]$$

$$\text{d.h. } f_A(x) = x \quad \forall x \in [G_1]$$

$$\angle(x, f_A(x)) = \varphi \quad \forall x \in [G_1]^\perp \setminus \{0\}$$

$\Rightarrow A$ beschreibt Drehung.

12.5.2) a) $p: V \rightarrow V$ Projektion.

ZZ: $\exists \hat{p}: V \rightarrow V$ zu p adjungiert $\Rightarrow \hat{p}$ Projektion.

p Projektion $\Rightarrow p \circ p = p \Rightarrow \hat{p} = \widehat{p \circ p} = \hat{p} \circ \hat{p} \Rightarrow \hat{p}$ Projektion.

b) \hat{p} Orthogonalprojektion $\Leftrightarrow p$ selbstadjungiert

" \Rightarrow " wurde bereits in Satz 12.5.3 gezeigt

" \Leftarrow " $p = \hat{p} \Rightarrow (p(V))^\perp = \text{Ker } \hat{p} = \text{Ker } p \Rightarrow p(V) \perp \text{Ker } p$, also p Ortho-Proj.

c) Sei V innerprodukt, p Projektion.

ZZ: p ist Orthogonalprojektion $\Leftrightarrow p$ normal

" \Rightarrow " p Orthoproj $\xrightarrow{c)}$ $p = \hat{p} \Rightarrow p \circ \hat{p} = p \circ p = \hat{p} \circ p$

$\Rightarrow p$ normal

" \Leftarrow " p normal: $\langle p(v), p(v) \rangle = \langle v, (\hat{p} \circ p)(v) \rangle = \langle v, (p \circ \hat{p})(v) \rangle = \langle \hat{p}(v), \hat{p}(v) \rangle$

$\Rightarrow \|p(v)\| = \|\hat{p}(v)\| \Rightarrow \text{Ker } p = \text{Ker } \hat{p}$

$\Rightarrow \text{Ker } p = (p(V))^\perp$

Voraussetzung $\Rightarrow V = \text{Ker } p \oplus p(V) \Rightarrow p$ ist Ortho.-Proj.

12.5.4) $A_1 = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{pmatrix} \in \mathbb{R}^{3 \times 3}$

$A_2 = \begin{pmatrix} 1 & i & -i \\ -i & 2 & 0 \\ i & 0 & 2 \end{pmatrix} \in \mathbb{C}^{3 \times 3}$

ges: $P \in O_3: P^{-1} A_1 P = \text{diag}(A_1, A_2, A_3)$

$$\chi_{A_1} = \det(A_1 - xE_3) = \begin{vmatrix} 1-x & 0 & 1 \\ 0 & 1-x & 1 \\ 1 & 1 & -x \end{vmatrix} = (-x)(1-x)^2 - (1-x) - (1-x) \\ = (1-x)(x^2 - x - 2) \\ = (1-x)(x+1)(x-2)$$

$\Rightarrow A_1 = 1, A_2 = -1, A_3 = 2$

EW zu A_1 : LGS: $\begin{array}{ccc|c} x_1 & x_2 & x_3 & \\ \hline 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 1 & -1 & 0 \end{array} \Rightarrow \mathcal{B}_1 = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$

EV zu A_2 : $\begin{array}{ccc|c} 2 & 0 & 1 & \\ \hline 0 & 2 & 1 & 0 \\ 1 & 1 & 1 & \end{array} \Rightarrow \mathcal{B}_2 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$

EV zu A_3 : $\begin{array}{ccc|c} -1 & 0 & 1 & \\ \hline 0 & -1 & 1 & 0 \\ 1 & 1 & -2 & \end{array} \Rightarrow \mathcal{B}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

⇒ Basis aus EV ist OGB, Transformation in ONB durch Normierung:

$$\|b_1\| = \sqrt{2}, \quad \|b_2\| = \sqrt{6}, \quad \|b_3\| = \sqrt{3}$$

$$\Rightarrow P := \frac{1}{\sqrt{6}} \begin{pmatrix} \sqrt{3} & 1 & \sqrt{2} \\ -\sqrt{3} & 1 & \sqrt{2} \\ 0 & -2 & \sqrt{2} \end{pmatrix} \in O_3$$

ges.: $Q \in U_3: Q^{-1} A_2 Q = \text{diag}(A_1, A_2, A_3)$

$$\chi_{A_2} = \det(A_2 - X E_3) = \begin{vmatrix} 1-X & i & -i \\ -i & 2-X & 0 \\ i & 0 & 2-X \end{vmatrix} = (1-X)(2-X)^2 - (2-X) - (2-X) \\ = (2-X)(X^2 - 3X + 2 - 2) \\ = X(2-X)(-3+X)$$

$$\Rightarrow A_1 = 0, \quad A_2 = 2, \quad A_3 = 3$$

EV zu A_1 : LGS

x_1	x_2	x_3	
1	i	$-i$	$\left. \begin{matrix} 0 \\ 0 \\ 0 \end{matrix} \right\} \begin{matrix} - \\ + \\ + \end{matrix}$
$-i$	2	0	
i	0	2	
0	$-i$	i	$\Rightarrow c_1 = \begin{pmatrix} 2i \\ -1 \\ 1 \end{pmatrix}$
$-i$	2	0	
0	2	2	

EV zu A_2 :

-1	i	$-i$	$\left. \begin{matrix} 0 \\ 0 \\ 0 \end{matrix} \right\} \Rightarrow c_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$
$-i$	0	0	
i	0	0	

EV zu A_3 :

-2	i	$-i$	$\left. \begin{matrix} 0 \\ 0 \\ 0 \end{matrix} \right\} \Rightarrow c_3 = \begin{pmatrix} i \\ 1 \\ -1 \end{pmatrix}$
$-i$	-1	0	
i	0	-1	

$$\|c_1\| = \frac{1}{\sqrt{6}}, \quad \|c_2\| = \sqrt{2}, \quad \|c_3\| = \sqrt{3}$$

$$\Rightarrow Q := \frac{1}{\sqrt{6}} \begin{pmatrix} 2i & 0 & \sqrt{2}i \\ -1 & \sqrt{3} & \sqrt{2} \\ 1 & \sqrt{3} & \sqrt{2} \end{pmatrix} \in U_3$$

12.4.7) $K = GF(4)$, $W = GF(4)^{2 \times 1}$, $\nu(E_1 E) = E_2$

a) $w = id_{GF(4)^{2 \times 1}}$

(i) ges.: alle ONB, d.h. $B = (b_1, b_2)$ mit

$$b_1 \perp b_2 \Leftrightarrow b_1 \cdot b_2 = 0 \Leftrightarrow x_1 y_1 + x_2 y_2 = 0 \Leftrightarrow x_1 y_1 = x_2 y_2$$

$$\|b_1\| = \sqrt{x_1^2 + x_2^2} = 1 \Leftrightarrow x_1^2 + x_2^2 = 1$$

$$\|b_2\| = 1 \Leftrightarrow y_1^2 + y_2^2 = 1$$

$$x_1^2 + x_2^2 = 1 \Leftrightarrow \begin{cases} x_1^2 = 1, & x_2^2 = 0 \\ x_1^2 = 0, & x_2^2 = 1 \\ x_1^2 = a, & x_2^2 = b \\ x_1^2 = b, & x_2^2 = a \end{cases} \Leftrightarrow \begin{cases} x_1 = 1, & x_2 = 0 \\ x_1 = 0, & x_2 = 1 \\ x_1 = a, & x_2 = a \\ x_1 = a, & x_2 = b \end{cases}$$

$$\Rightarrow \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_{=: M_1}, \underbrace{\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}}_{=: M_2}, \underbrace{\begin{pmatrix} a & b \\ b & a \end{pmatrix}}_{=: M_3}, \underbrace{\begin{pmatrix} b & a \\ a & b \end{pmatrix}}_{=: M_4}$$

da alle anderen Basen mit $\|b_1\| = \|b_2\| = 1$ die \perp -Relation nicht erfüllen.

(ii) Verknüpfungstafel von $O_2(\text{GF}(4))$:

$$O_2(\text{GF}(4)) = \{M_1, M_2, M_3, M_4\}; \quad (R) := \begin{pmatrix} R & R \\ R & R \end{pmatrix} \quad \forall R \in \text{GF}(4)$$

+	M_1	M_2	M_3	M_4
M_1	(0)	(1)	(e)	(a)
M_2	(1)	(0)	(a)	(b)
M_3	(e)	(a)	(0)	(1)
M_4	(a)	(b)	(1)	(0)

•	M_1	M_2	M_3	M_4
M_1	M_1	M_2	M_3	M_4
M_2	M_2	M_1	M_4	M_3
M_3	M_3	M_4	M_1	M_2
M_4	M_4	M_3	M_2	M_1

6) $\omega: x \mapsto x^2$

(i) ges: alle ONB, d.h. $B = (b_1, b_2)$ mit

$$b_1 \perp b_2 \Leftrightarrow x_1^2 y_1 + x_2^2 y_2 = 0 \Leftrightarrow x_1^2 y_1 = x_2^2 y_2$$

$$\|b_1\| = 1 \Leftrightarrow x_1^3 + x_2^3 = 1$$

$$\|b_2\| = 1 \Leftrightarrow y_1^3 + y_2^3 = 1$$

$$x_1^3 = \begin{cases} 0 & x_1 = 0 \\ 1 & x_1 \neq 0 \end{cases} \Rightarrow x_1^3 + x_2^3 = 1 \Leftrightarrow \begin{cases} x_1 = 0, & x_2 \neq 0 \\ x_1 \neq 0, & x_2 = 0 \end{cases}$$

$$x_1 \neq 0 \Rightarrow x_2 = 0 \stackrel{\perp}{\Rightarrow} y_1 = 0 \Rightarrow y_2 \neq 0 \quad \text{o. B. d. A.}$$

$$\Rightarrow O_2(\text{GF}(4), \omega) = \left\{ \begin{pmatrix} R_{11} & 0 \\ 0 & R_{22} \end{pmatrix} \mid R_{11}, R_{22} \in \text{GF}(4) \setminus \{0\} \right\}$$

$$\left\{ \begin{pmatrix} 0 & R_{12} \\ a & b \end{pmatrix} \mid a, b \in \text{GF}(4) \right\}$$

(ii) Verknüpfungstafeln von $O_2(GF(4), w)$

$$\begin{array}{c}
 + \\
 \left(\begin{array}{c|c|c}
 \begin{pmatrix} R_{11} & 0 \\ 0 & R_{22} \end{pmatrix} & \begin{pmatrix} 0 & R_{12} \\ R_{21} & 0 \end{pmatrix} & \\
 \hline
 \begin{pmatrix} R_{11} & 0 \\ 0 & R_{22} \end{pmatrix} & (0) & \begin{pmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{pmatrix} \\
 \hline
 \begin{pmatrix} 0 & R_{12} \\ R_{21} & 0 \end{pmatrix} & \begin{pmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{pmatrix} & (0)
 \end{array} \right)
 \end{array}
 \quad
 \begin{array}{c}
 \cdot \\
 \left(\begin{array}{c|c|c}
 \begin{pmatrix} R_{11} & 0 \\ 0 & R_{22} \end{pmatrix} & \begin{pmatrix} 0 & R_{12} \\ R_{21} & 0 \end{pmatrix} & \\
 \hline
 \begin{pmatrix} R_{11} & 0 \\ 0 & R_{22} \end{pmatrix} & \begin{pmatrix} R_{11}^2 & 0 \\ 0 & R_{22}^2 \end{pmatrix} & \begin{pmatrix} 0 & R_{11} R_{12} \\ R_{22} R_{21} & 0 \end{pmatrix} \\
 \hline
 \begin{pmatrix} 0 & R_{12} \\ R_{21} & 0 \end{pmatrix} & \begin{pmatrix} 0 & R_{12} R_{22} \\ R_{11} R_{21} & 0 \end{pmatrix} & \begin{pmatrix} R_{12} R_{21} & 0 \\ 0 & R_{12} R_{21} \end{pmatrix}
 \end{array} \right)
 \end{array}$$

12.5.8) $f: \mathbb{R}^{3 \times 1} \mapsto \mathbb{R}^{3 \times 1}$

$$\langle E^*, f(E) \rangle = \frac{1}{4} \begin{pmatrix} 1 & 5 & \sqrt{2}+4 \\ -3 & 1 & \sqrt{2}+8 \\ \sqrt{2}-4 & \sqrt{2}-8 & 2 \end{pmatrix}$$

A 9.4.2 c): Jede Matrix $\in K^{n \times n}$ kann eindeutig als Summe einer symm. und einer schiefymm. Matrix dargestellt werden.

Satz 12.3.5: $\langle B^*, f(B) \rangle$ symm. $\Leftrightarrow f$ selbstadj.
 ————— schiefymm. $\Leftrightarrow f$ antiselbstadj.

vgl. A 9.4.2 b)

$$\begin{aligned}
 \langle E^*, f_1(E) \rangle & \stackrel{\downarrow}{=} \frac{1}{2} (\langle E^*, f(E) \rangle + \langle E^*, f(E) \rangle^T) \\
 & = \frac{1}{8} \begin{pmatrix} 2 & 2 & 2\sqrt{2} \\ 2 & 2 & 2\sqrt{2} \\ 2\sqrt{2} & 2\sqrt{2} & 4 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1 & 1 & \sqrt{2} \\ 1 & 1 & \sqrt{2} \\ \sqrt{2} & \sqrt{2} & 2 \end{pmatrix}
 \end{aligned}$$

$$\begin{aligned}
 \langle E^*, f_2(E) \rangle & = \frac{1}{2} (\langle E^*, f(E) \rangle - \langle E^*, f(E) \rangle^T) \\
 & = \frac{1}{8} \begin{pmatrix} 0 & 8 & 8 \\ -8 & 0 & 16 \\ -8 & 16 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 1 \\ -1 & 0 & 2 \\ -1 & -2 & 0 \end{pmatrix}
 \end{aligned}$$