Differentialgleichungen UE

IX, 250, 251, 255, 259, 263, 270

=>
$$\mathcal{L}(\bar{x})(u) + \mathcal{L}(\bar{x})(u) + 3\mathcal{L}(\bar{x})(u) + \mathcal{L}(\bar{x})(u) = \mathcal{L}(\cos A)(u) = \frac{u}{u^2+1}$$

$$\mathcal{L}(\dot{\mathbf{x}})(\mathbf{u}) = u \, \mathcal{L}(\mathbf{x})(\mathbf{u}) - \mathbf{x}(\mathbf{0}) = u \, \mathcal{L}(\mathbf{x})(\mathbf{u}) - 1$$

$$L(\bar{x})(u) = u L(\bar{x})(u) - \bar{x}(0) = u^2 L(x)(u) - du - 2$$

$$\mathcal{L}(4\times)(n) = -\frac{d}{dn} \mathcal{L}(\times)(n)$$

$$\mathcal{L}(4x)(u) = -\frac{d}{du} \mathcal{L}(x)(u) = -\mathcal{L}(x)(u) - u \frac{d}{du} \mathcal{L}(x)(u)$$

$$u^{2} \mathcal{L}(x)(u) - u - 2 - u \mathcal{L}(x)(u) + 1 - 3 \mathcal{L}(x)(u) - 3u \frac{d}{du} \mathcal{L}(x)(u) - \frac{d}{du} \mathcal{L}(x)(u) = \frac{u}{u^{2} + 1}$$

$$\Leftrightarrow$$
 -(3u+1) $\hat{\mathcal{L}}(x) + (u^2 - u - 3) \mathcal{L}(x) = \frac{u}{u^2 + 1} + u + 1$

251)
$$\left(\frac{\dot{x}}{y}\right) = \left(\frac{2}{3} - 6\right) \left(\frac{x}{y}\right) + \left(\frac{14}{13}\right) \sin 4$$

") Lösungsleesin d. hom. DGL

$$\chi_{A}(\lambda) = \lambda^{2} + 2\lambda + 10 = 0 \Leftrightarrow \lambda = -1 \pm \sqrt{1-10} = -1 \pm 3i$$

$$\operatorname{Ren}(A - (-1 \pm 3i)E) = \operatorname{Ren}\begin{pmatrix} 3-3i & -6 \\ 3 & -3-3i \end{pmatrix} = \operatorname{Ren}\begin{pmatrix} 1-i & -2 \\ 1 & -1-i \end{pmatrix} = \begin{bmatrix} 1+i \\ 1 \end{bmatrix}$$

$$\rightarrow W(4) = Te^{+j} = \left(\begin{pmatrix} 1+i \\ 1 \end{pmatrix} e^{(-1+3i)t}, \begin{pmatrix} 1-i \\ 1 \end{pmatrix} e^{(-1-3i)t} \right)$$

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e) press. Löning
     i + EW => Ansatz x = of sint + of cost
                                                  y = or sint + tr cost
      σ (σ, cost - τ, sint = 2(σ, sint + τ, cost) - 6(σ, sint + τ, cost) + 14 sint

σ, cost - τ, sint = 3( - " - ) - 4( - " - ) + 13 sint
      \begin{cases} 0 = (\tau_1 + 2\sigma_1 - 6\sigma_2 + 14) \sin t + (-\sigma_1 + 2\tau_1 - 6\tau_2) \cos t \\ 0 = (\tau_2 + 3\sigma_1 - 4\sigma_2 + 13) \sin t + (-\sigma_2 + 3\tau_1 - 4\tau_2) \cos t \end{cases}
                   O1 O1 T1 T1
                          0 2 -6
                   0 -6 -12 -14 26
                          -4 6 -17 -13
                   0 1 -3 4 0 6
                                                              -13
                                     -6 -1
                   1 0 -38 0 -78
                                                                                   => T1 = 2, T2 = 13-6T1 = 1
                          1 -27 0
                                                                                         On = -78+38= = -2
                                                               -52
                           0 -85 0
                                                              -170
                                                                                       02 = -52 + 27= 2
      \Rightarrow \varphi_{p} = \begin{pmatrix} -2\sin t + 2\cos t \\ 2\sin t + \cos t \end{pmatrix}
2) Rondmersmoblem
      C \cdot \varphi(0) + D \cdot \varphi(\pi) = c \Leftrightarrow C(W(0) \sigma + \varphi_{pr}(0)) + D(W(\pi) \sigma + \varphi_{pr}(\pi)) = c
\Leftrightarrow \underbrace{(CW(0) + DW(\pi))}_{R(W)} \sigma = c - \underbrace{(C\varphi_{pr}(0) + D\varphi_{pr}(\pi))}_{R(\varphi_{pr})}
     R(w) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} + \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} -e^{-\tau} & -e^{-\tau} \\ -e^{-\tau} & 0 \end{pmatrix} = \begin{pmatrix} 1 + e^{-\tau} & 1 + e^{-\tau} \\ 1 & 0 \end{pmatrix}
     R(\varphi_w) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} -2 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 1 \end{pmatrix}
     R(w) regular => \left(\sigma_{1}\right) = R(w)^{-1} \left(\mathbf{c} - R(\varphi_{P})\right)
                                                     = -\frac{1}{1+e^{-\tau}} \begin{pmatrix} 0 & -1-e^{-\tau} \\ -1 & 1+e^{-\tau} \end{pmatrix} \begin{pmatrix} -4 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ -\frac{4}{1+e^{-\tau}} \end{pmatrix}.
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 $\Rightarrow \begin{pmatrix} \times \\ y \end{pmatrix} = \begin{pmatrix} e^{+}\cos 3t - e^{+}\sin 3t & e^{-t}\sin 3t + e^{-t}\cos 3t \\ e^{-t}\cos 3t & e^{-t}\sin 3t \end{pmatrix} \begin{pmatrix} 0 \\ -\frac{4}{1+e^{-t}} \end{pmatrix} + \begin{pmatrix} -2\sin t + 2\cos t \\ 2\sin t + \cos t \end{pmatrix}$

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259, x^{(3)} + \dot{x} + \dot{x} + x = e^{-t} - 1
                                                       \begin{array}{l} x(0)=1 \\ x(\pi)=e^{-\pi}+1 \\ \dot{x}(0)=\dot{x}(\pi) \end{array}, \quad \begin{array}{l} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{array} \begin{pmatrix} x \\ \dot{x} \\ 0 \end{pmatrix} (0) + \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ \dot{x} \\ \ddot{x} \end{pmatrix} (\pi) = \begin{pmatrix} 1 \\ e^{-\pi}+1 \\ 0 \end{pmatrix}
                                                       Winsen sous Byg. 243j: W(4) = \begin{pmatrix} e^{-4} & \cos 4 & \sin 4 \\ -e^{-4} & -\sin 4 & \cos 4 \\ e^{-4} & -\cos 4 & -\sin 4 \end{pmatrix}
                                                     = \begin{pmatrix} 1 & 1 & 0 \\ e^{-\overline{v}} & -1 & 0 \end{pmatrix} is regular \Rightarrow \exists ! Lösung des RWP.
                   263) G(4, u) = W(4) (2(4, u) · E - R(W) - D· W(7)) · W - (u)
                                                                                                                                                                               = M(4,u)
                                                  R(w)^{-1}Dw(\pi) = \frac{1}{2(1+e^{-\pi})} \begin{pmatrix} 2 & 2 & 0 & 0 & 0 \\ 2e^{-\pi} & 2 & 0 & e^{-\pi} & -1 & 0 \\ 1-e^{-\pi} & 1-e^{-\pi} & 1+e^{-\pi} & e^{-\pi} & 0 & 1 \end{pmatrix}
                                                                                                                =\frac{1}{2(1+e^{-\pi})}\begin{pmatrix} 2e^{-\pi} & -2 & 0 \\ -2e^{-\pi} & 2 & 0 \\ 2e^{-\pi} & e^{\pi} - 1 & 1+e^{\pi} \end{pmatrix}
                                                w^{-1}(u) = \frac{1}{2} \begin{cases} e^{u} & 0 & e^{u} \\ -\sin u + \cos u & -2\sin u & -\cos u - \sin u \\ \cos u + \sin u & 2\cos u & -\sin u + \cos u \end{cases}
                                                G(4,u) = \begin{cases} G(4,u) := & G(4,u) := \\ W(4) (R(w)^{-1} D W(\pi)) W^{-1}(u) & O \le 4 < u \le \pi \\ W(4) W^{-1}(u) + G_{1}(4,u) & O \le u \le 4 \le \pi \end{cases}
                                                  \Rightarrow \Gamma_{1}(4,u) = -\frac{1}{4(1+e^{-\frac{1}{4}})} \left(e^{-\frac{1}{4}}, \cos t_{1} \sin t\right) \left(\frac{2e^{-\frac{1}{4}}}{2e^{-\frac{1}{4}}} - \frac{2}{2} + \frac{0}{2}\right) \left(e^{u} - \cos u + \sin u\right) \left(\frac{2e^{-\frac{1}{4}}}{2e^{-\frac{1}{4}}} - \frac{1}{2} + \frac{1}{2}\right) \left(\frac{e^{u}}{2e^{-\frac{1}{4}}} - \frac{1}{2} + \frac{1}{2}\right) \left(\frac{e^{u}}{2e^{-\frac{1}{4}}} - \frac{1}{2} + \frac{1}{2}\right) \left(\frac{e^{u}}{2e^{-\frac{1}{4}}} - \frac{1}{2
                                                                                                       = - 1 (e-+(ew+cosu+sinu)-cost (ew+cosu+sinu)
                                                                                                                                                                               + sint (ent + cosu - et sinu))
                                                                                                                                                                                                                                                                                                                                                                                                                        0 = 4 < WETT
                                                                  \Gamma_2(A,u) = \frac{1}{2}(e^{-t}, \cos t, \sin t) \left(-\cos u - \sin u\right) + \Gamma_1(A,u)
                                                                                                       = = 1 (1+e-+) (-(1+e-+) eu-+ + (1+e-+) cost (cosu+ sin u) - (1+e-+) sint (cosu-sinu)
                                                                                                                      + e-+ (eu-++ cosu+sinu)-eus 4 (eu++ cosu+sinu)+sin 4 (eu++cosu-e-* sinu))
= - 1 (e-4 (-e"+cosu+sinu)-cos 4(e"-"-e"(cosu+sinu)+sin4(e"+sinu-e"cosu)) Osuston
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270, x+2x-8x+ 1x=0 ×(1)=0 ×(0)=0 Char. Bolynom d. agu. Systems 1. Ordnung: $\chi_{A}(x) = x^{2} + 2x - 8 + 2x - 8 + 2x = 0$ $\iff x = -1 \pm \sqrt{1 + 8 - \lambda}' = -1 \pm \sqrt{9 - \lambda}'$ 1. Fall: 9-x > 0 @ x < 9 Sei a:= 19-11 > 0 => \(\phi(4) = \sigma_1 e^{(-1+a)t} + \sigma_2 e^{(-1-a)t} RB = (\phi(1) = o1 e^{-1+a} + o2 e^{-1-a} = 0 & o1 = -o2 e^{-2a} (0)= (-1+a) on + (-1-a) or =0 ~ (1-0) oz e^{-2a} = (+1+a) oz ⇔ a=0 y zu VS → fin λ<9 existing Beine nicht shirinele dissung. 2. Fell: X=9 => -1 is doggether EW => \(\phi(4) = \sigma_1 e^{-4} + \sigma_2 t e^{-t} \) RB = ((1) = 0, e-1+02e-1=0 = -01=02 ⇒ Ø1 = Ø2 = O. (\$(0)= -01 + 01=0 € 01=01 3. Foll: => \(\psi(4) = \si_1 e^{-4} \cos 64 + \si_2 e^{-4} \sin 64 \$\$ df(4) = - o1 e-4 cos 64 - 6 o1 e-4 sin 64 - o1 e-4 sin 64 + 6 o1 e-4 cos 64

 $\Rightarrow \varphi(A) = \varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\Re \varphi(A) = -\varphi_1 e^{-4} \cos 64 - 6 \varphi_1 e^{-4} \sin 64 - \varphi_2 e^{-4} \sin 64 + 6 \varphi_1 e^{-4} \cos 64$ $RB = \varphi(A) = \varphi_1 e^{-4} \cos 64 - 6 \varphi_1 e^{-4} \sin 64 - \varphi_2 e^{-4} \sin 64 + 6 \varphi_1 e^{-4} \cos 64$ $RB = \varphi(A) = \varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64 - \varphi_2 e^{-4} \sin 64 + 6 \varphi_1 e^{-4} \cos 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \sin 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e^{-4} \cos 64 + \varphi_2 e^{-4} \cos 64$ $\varphi(A) = -\varphi_1 e^{-4} \cos 64 + \varphi_2 e$

~ 6 og e ω 6 + or e sin 6 = 0 (=) Vλ-9 cos Vλ-9 + sin Vλ-9 = 0 (λ>9)